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with initial conditions $x_1(0) = y_0$ and $x_2(0) = y_1$. Since $y(t)$ is of interest, the output equation $y(t) = x_1(t)$ is alsoadded. These can be written as which are of the general form Here $x(t)$ is a 2×1 vector (a column vector) with elements the two state variables $x_1(t)$ and $x_2(t)$. It is called the state vector. The variable $u(t)$ is the input and $y(t)$ is the output of the system.